Eco 4306 Economic and Business Forecasting Lecture 16 Chapter 10: Forecasting the Long Term: Deterministic and Stochastic Trends

Motivation

- \triangleright ARMA models require the data are to be second order weakly stationary
- \blacktriangleright they thus can not be used for time series that grow over time, unless we transform them (by taking first differences, or using log and then taking first differences)
- \triangleright our next goal is to learn how to analyze nonstationary data account for the persistent upward or downward tendency in many economic and business time series

Overview

main objectives of Chapter 10

- 1. understand deterministic and stochastic trends, construct models that produce these trends and analyze their properties and forecasts
- 2. design statistical procedures to detect deterministic and stochastic trends in the data

10.1 Deterministic Trends

 \triangleright simple linear model with a deterministic trend

$$
Y_t = \beta_0 + \beta_1 t + \varepsilon_t
$$

where β_0 is the intercept and β_1 slope and ε_t a white noise error

 \triangleright but trends can have different shapes, linear trend is just one particular case

 \triangleright more generally, a model with deterministic trend can be written as

$$
Y_t = g(t) + \varepsilon_t
$$

where $g(t)$ is some function that specifies the deterministic trend

U.S. Nonfarm Business Sector, Output and Productivity, Indices, 1947Q1=100

Real Output **-** Output per Hour

U.S. Nonfarm Business Sector, Employment and Hours, Indices, 1947Q1=100

 2000 2010 2020 Consumer Price Index: Information technology

6 / 32

Average Number of People Living in U.S.a Household

Relative Labor Force Participation Rate: Women/Men

Employment in Manufacturing

Relative to Overall Employment - Relative to Total Population

Held By Public - Total $\overline{}$

U.S. Real GDP, in billions of 2009 dollars

most common trend specifications

- Inear trend, $g(t) = \beta_1 t$
- **I** quadratic trend, $g(t) = \beta_0 + \beta_1 t + \beta_2 t^2$
- \triangleright polynomial trend, *g*(*t*) = *β*₀ + *β*₁*t* + *β*₂*t*² + . . . + *β*_{*ntⁿ*}
- **P** exponential trend, $g(t) = \beta_0 e^{\beta_1 t}$

$$
\blacktriangleright \text{ logistic trend, } g(t) = \frac{\beta_2}{1 + \beta_0 e^{\beta_1 t}}
$$

simulated series $Y_t = g(t) + \varepsilon_t$ for different trend specifications

simulated series $Y_t = g(t) + \varepsilon_t$ for different trend specifications

10.1.2 Trend Stationarity

If consider a process with a deterministic trend, $Y_t = g(t) + \varepsilon_t$, where ε_t is white noise

 \blacktriangleright the unconditional mean is

$$
\mu_t = E(Y_t) = E(g(t) + \varepsilon_t) = E(g(t)) + E(\varepsilon_t) = g(t)
$$

 \blacktriangleright the unconditional variance is

$$
\gamma_0 = var(Y_t) = E[(Y_t - \mu_t)^2] = E[\varepsilon_t^2] = \sigma_{\varepsilon}^2
$$

E autocovariance of order k is

$$
\gamma_k = E[(Y_t - \mu_t)(Y_{t-k} - \mu_{t-k})] = E[\varepsilon_t \varepsilon_{t-k}] = 0
$$

 \blacktriangleright autocorrelation of order k is

$$
\rho_k=\frac{\gamma_k}{\gamma_0}=0
$$

10.1.2 Trend Stationarity

- In thus the unconditional mean μ_t is time varying, but the unconditional variance is not, and the auto-covariance and autocorrelation functions do not depend on time
- \triangleright because the mean of a process Y_t is not constant over time, it is not first order weakly stationary process
- \triangleright but because the variance and autocovariances satisfy the requirements for second order weak stationarity, the detrended process, $\tilde{y}_t = y_t - \mu_t$, that is, $\tilde{y}_t = y_t - g(t)$, is second order weakly stationary, and we say that y_t is **trend-stationary**

10.1.3 Optimal Forecast

- \blacktriangleright recall: under quadratic loss function the optimal forecast is the conditional mean $f_{t,h} = \mu_{t+h|t} = E(Y_{t+h}|I_t)$ for $h = 1, 2, ..., s$
- \triangleright we next analyze this optimal forecast under quadratic loss function for $h = 1, 2, \ldots$

10.1.3 Optimal Forecast

if $Y_t = g(t) + \varepsilon_t$ where ε_t is white noise, for the forecasting horizon $h = 1$ we have 1. optimal point forecast

$$
f_{t,1} = \mu_{t+1|t} = E(Y_{t+1}|I_t) = E(g(t+1) + \varepsilon_{t+1}|I_t) = g(t+1)
$$

2. forecast error

$$
e_{t,1} = Y_{t+1} - f_{t,1} = g(t+1) + \varepsilon_{t+1} - g(t+1) = \varepsilon_{t+1}
$$

3. uncertainty associated with the forecast is summarized by the variance of the forecast error

$$
\sigma_{t+1|t}^2 = var(e_{t,1}|I_t) = var(\varepsilon_{t+1}) = \sigma_{\varepsilon}^2
$$

4. the density forecast is the conditional probability density function $f(Y_{t+1}|I_t)$, assuming ε_{t+1} is normally distributed white noise, we have

$$
Y_{t+1}|I_t \sim N(g(t+1), \sigma_{\varepsilon}^2)
$$

10.1.3 Optimal Forecast

in general if $Y_t = g(t) + \varepsilon_t$ where ε_t is white noise, for the forecast at horizon $h = s$ we have

$$
f_{t,s} = g(t+s)
$$

$$
e_{t,s} = \varepsilon_{t+s}
$$

$$
\sigma_{t+s|t}^2 = \sigma_{\varepsilon}^2
$$

$$
Y_{t+s}|I_t \sim N(g(t+s), \sigma_{\varepsilon}^2)
$$

- \triangleright note that the uncertainty of the forecast is thus same regardless of the forecasting horizon, because we assumed that *εt* is white noise
- \triangleright in general, model with deterministic trend can accommodate linear dependence in its stochastic component: instead of $Y_t = g(t) + \varepsilon_t$ where ε_t is white noise, we then have $Y_t = q(t) + u_t$ where u_t follows some ARMA (p, q) model

- \blacktriangleright time series plot shows that earnings per share of Johnson and Johnson grew exponentially in the period from 1960Q1 to 1980Q4
- \triangleright in addition, there is a seasonal pattern that will need to be incorporated into the estimated model

- \triangleright to build a model for forecasting, we start by generating time series for trend: choose **Object** → **Generate Series** and enter t = @trend
- \blacktriangleright to estimate a model with exponential trend

$$
JNJ_t = \beta_0 + \beta_1 e^{\beta_2 t} + \varepsilon_t
$$

choose **Object** \rightarrow **New Object** \rightarrow **Equation**, in the Equation specification box enter JNJ = $c(1) + c(2) * exp(c(3) * t)$ and in Sample 1960Q1 1978Q4

```
Dependent Variable: JNJ
Method: Least Squares (Gauss-Newton / Marquardt steps)
Date: 03/22/19 Time: 00:23
Sample: 1960Q1 1978Q4
Included observations: 76
Convergence achieved after 23 iterations
Coefficient covariance computed using outer product of gradients
JNJ = C(1) + C(2)*EXP(C(3)*T)
```


the plot with actual vs fitted data and the regression residuals, which can be obtained by selecting **View** → **Actual, Fitted, Residual** → **Actual, Fitted, Residual Graph** reveals two problems with the estimated model:

- \blacktriangleright it can match the trend, but not the seasonal pattern
- \blacktriangleright the variance of residuals does not appear to be constant, it is increasing over time

 \triangleright to deal with issue of variance of residuals increasing over time we reestimate the model using log transformed data

$$
\log JNJ_t = \beta_0 + \beta_1 t + \varepsilon_t
$$

- \blacktriangleright note that this is equivalent to a multiplicative model $JNJ_t = \tilde{\beta}_0 e^{\beta_1 t} \tilde{\varepsilon}_t$ where $\tilde{\beta}_0 = e^{\beta_0}$ and $\tilde{\varepsilon}_t = e^{\varepsilon_t}$
- $▶$ to estimate this model choose Object $→$ New Object $→$ Equation, in the Equation specification box write log(JNJ) c t and in Sample 1960Q1 1978Q4

Dependent Variable: LOG(JNJ) Method: Least Squares Date: 03/22/19 Time: 00:23 Sample: 1960Q1 1978Q4 Included observations: 76

residuals shows that the variance is now roughly same over time, but the model still can not match the seasonal pattern

- If this finding is supported by the correlogram, obtained using $View \rightarrow Residual$ **Diagnostics** → **Correlogram - Q-statistics**, which shows large significant component of PACF at lag 4, and significant components of ACF at lags 4, 8, 12
- \blacktriangleright the residuals are thus not white noise

Date: 03/22/19 Time: 00:23 Sample: 1960Q1 1978Q4 Included observations: 76

 \triangleright we thus include the seasonal term in the specification of the innovation u_t

$$
\log JNJ_t = \beta_0 + \beta_1 t + u_t
$$

$$
u_t = \phi_4 u_{t-4} + \varepsilon_t
$$

 $▶$ to do this choose Object $→$ New Object $→$ Equation , in the Equation specification box enter $log(JNJ)$ c t sar(4) and in Sample 1960Q1 1978Q4

> Dependent Variable: LOG(JNJ) Method: ARMA Maximum Likelihood (OPG - BHHH) Date: 03/22/19 Time: 00:23 Sample: 1960Q1 1978Q4 Included observations: 76 Convergence achieved after 20 iterations Coefficient covariance computed using outer product of gradients

residuals no longer have any recognizable seasonal pattern

but the first lag in the ACF and PACF is significant, resulting in p-values for Ljung-Box test that are lower than 0.05

> Date: 03/22/19 Time: 00:23 Sample: 1960Q1 1978Q4 Included observations: 76 Q-statistic probabilities adjusted for 1 ARMA term

*Probabilities may not be valid for this equation specification.

If to fix this issue we include the first regular AR lag in the model, so that u_t is now given by a multiplicative $AR(1)+SAR(1)$ specification

$$
\log JNJ_t = \beta_0 + \beta_1 t + u_t
$$

$$
u_t = \phi_1 u_{t-1} + \phi_4 u_{t-4} + \phi_1 \phi_4 u_{t-5} + \varepsilon_t
$$

 $▶$ to estimate this model choose Object $→$ New Object $→$ Equation, in the Equation specification box enter $log(JNJ)$ c t $ar(1)$ sar(4) and in Sample 1960Q1 1978Q4

Dependent Variable: LOG(JNJ) Method: ARMA Maximum Likelihood (OPG - BHHH) Date: 03/22/19 Time: 00:23 Sample: 1960Q1 1978Q4 Included observations: 76 Convergence achieved after 60 iterations Coefficient covariance computed using outer product of gradients

Variable	Coefficient	Std. Error	t-Statistic	Prob.
с	-0.525757	0.115973	-4.533449	0.0000
	0.039723	0.002461	16.14400	0.0000
AR(1)	0.297928	0.124682	2.389497	0.0195
SAR(4)	0863483	0.051306	1683009	0.0000
SIGMASO	0.008312	0.001298	6.401631	0.0000
R-squared	0.990659	Mean dependent var		0.945698
Adjusted R-squared	0.990133	S.D. dependent var		0949594
S.E. of regression	0.094326	Akaike info criterion		-1.747155
Sum squared resid	0.631709	Schwarz criterion		-1.593817
Log likelihood	71.39189	Hannan-Quinn criter.		-1.685874
F-statistic	1882 531	Durbin-Watson stat		1871645
Prob(F-statistic)	0.000000			
Inverted AR Roots	.96 -96	-30	$.00 - .96i$	$.00 + .96i$

residuals do not show any systematic pattern

correlogram also suggests that the residuals are white noise

Date: 03/22/19 Time: 00:23 Sample: 1960Q1 1978Q4 Included observations: 76 Q-statistic probabilities adjusted for 2 ARMA terms

*Probabilities may not be valid for this equation specification.

- ight to create *h*-quarter ahead forecasts for $h = 1, 2, \ldots, 12$, so 1979Q1-1981Q4: choose **Forecast** and set "Series to forecast" to "JNJ"","Method" to "Dynamic forecast" and "Forecast sample" to "1979Q1 1981Q4"
- ight to create a sequence of 1-quarter ahead forecasts, from $1979Q1-1981Q4$: choose **Forecast** and set "Series to forecast" to "JNJ"","Method" to "Static forecast" and "Forecast sample" to "1979Q1 1981Q4"

- \triangleright sequence of 1-step ahead forecasts is more precise than the multistep forecast -RMSE is 0.8480 for the former and 0.9913 for the latter
- \triangleright confidence interval is narrower in the case of the 1-step ahead forecasts
- \blacktriangleright multistep forecast is not able to account for a change in the seasonal pattern, 1-step ahead forecasts are eventually able to do that though with a one year delay

